



Relational Specification and Verification From Non-Interference to Regression-free Program Evolution

Bernhard Beckert with M. Kirsten, V. Klebanov, M. Ulbrich, A. Weigl | RS3 Practitioner Event





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Functional Verification:

Prove property for one program

Relational Verification:

Prove relation between two programs

Relational vs. Functional **Object-oriented Programs** ••••••

Programmable Logic Controllers

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Use Cases:

Non-interference / Information flow

Regression Verification

Relational Properties of Algorithms

Refinement

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Use Cases:

Non-interference / Information flow

$$\mathit{low}_1 = \mathit{low}_2 \ o \ \langle \mathit{P}_1; \mathit{P}_2
angle \ \mathit{low}_1 = \mathit{low}_2$$

Regression Verification

Relational Properties of Algorithms

Refinement

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Use Cases:

Non-interference / Information flow

$$low_1 = low_2 \rightarrow \langle P_1; P_2 \rangle low_1 = low_2$$

Regression Verification

$$in_P = in_Q \rightarrow \langle P; Q \rangle out_P = out_Q$$

Relational Properties of Algorithms

Refinement

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Use Cases:

Non-interference / Information flow

$$\mathit{low}_1 = \mathit{low}_2 \rightarrow \langle \mathit{P}_1; \mathit{P}_2 \rangle \mathit{low}_1 = \mathit{low}_2$$

Regression Verification

$$in_P = in_Q \rightarrow \langle P; Q \rangle out_P = out_Q$$

Relational Properties of Algorithms

 $ballots_1 \sim ballots_2 \rightarrow \langle P_1; P_2 \rangle$ winner₁ \approx winner₂

Refinement

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Use Cases:

Non-interference / Information flow

$$\mathit{low}_1 = \mathit{low}_2 \rightarrow \langle \mathit{P}_1; \mathit{P}_2 \rangle \mathit{low}_1 = \mathit{low}_2$$

Regression Verification

$$in_P = in_Q \rightarrow \langle P; Q \rangle out_P = out_Q$$

Relational Properties of Algorithms

 $\textit{ballots}_1 \sim \textit{ballots}_2 \rightarrow \langle P_1; P_2 \rangle \textit{ winner}_1 \approx \textit{winner}_2$

Refinement

$$\textit{in}_{\textit{Abs}} \sim \textit{in}_{\textit{Concr}} \rightarrow \langle \textit{Abs}; \textit{Concr} \rangle \textit{out}_{\textit{Abs}} \approx \textit{out}_{\textit{Concr}}$$

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Functional Verification:

Prove property for one program P

Relational Verification:

Prove relation between two programs P, Q

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Functional Verification:

Prove property for one program *P* Effort grows with size/complexity of *P*

Relational Verification:

Prove relation between two programs P, Q

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Functional Verification:

Prove property for one program *P* Effort grows with size/complexity of *P*

Relational Verification:

Prove relation between two programs P, QEffort grows with size/complexity of $\Delta(P, Q)$

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Functional Verification:

Prove property for one program *P* Effort grows with size/complexity of *P*

Relational Verification:

Prove relation between two programs P, QEffort grows with size/complexity of $\Delta(P, Q)$

Verification considers P, Q simultaneously!

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General Setting



- deductive reasoning
- about complex interferences / flows
- with high precision
- at program level
- "small" programs

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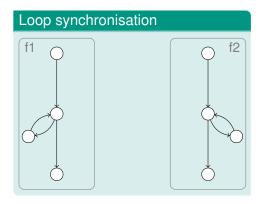
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Loop synchronisation f1 f2

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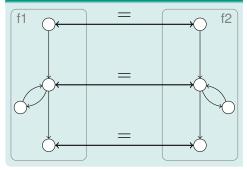
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Loop synchronisation



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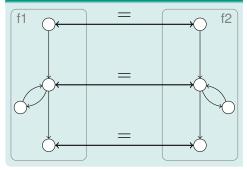
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Loop synchronisation



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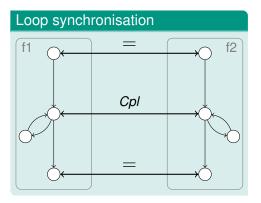
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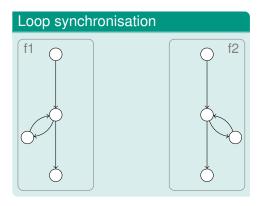
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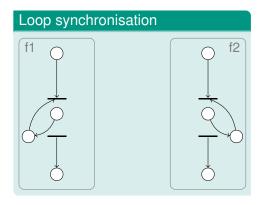
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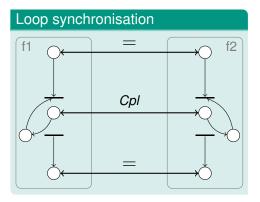
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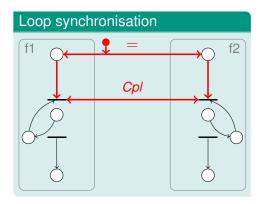
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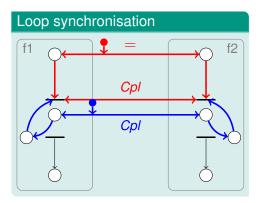
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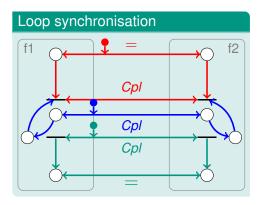
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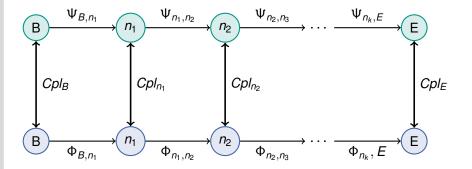
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Synchronised Traces







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www.key-project.org

Project Consortium

- Bernhard Beckert Karlsruhe Institute of Technology
- Reiner Hähnle TU Darmstadt
- Wolfgang Ahrendt Chalmers Univ., Gothenburg

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Deductive Verification of

Java

- Specification: Java Modeling Language
- Source-code level

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Deductive Verification of

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KeY Tool Deductive rules for all Java features ▲□ ▶ ▲ 三 ▶ ▲ 三 ▶ Relational vs. Functional **Object-oriented Programs** Programmable Logic Controllers C Programs Demo Reve Tool 0000 **BS3** Practitioner Event 9/29

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Deductive Verification of

Java

- Specification: Java Modeling Language
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KeY Tool

- Deductive rules for all Java features
- Symbolic execution

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Deductive Verification of

Java

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KeY Tool

- Deductive rules for all Java features
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- Java Card (Java 1.4)

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Deductive Verification of

Java

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KeY Tool

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Semi-automated

(automation and usability both important)

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Object-Sensitive Non-interference



Leakage by aliasing

```
void m() {
  C c1 = new C(); // new obj
  C c2 = c1;
            // alias
  c2.x = high;
  low = c1.x;
```

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Object-Sensitive Non-interference



Leakage by aliasing

```
void m() {
  C c1 = new C(); // new obj
  C c2 = c1;
                  // alias
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  c2.x = high;
  low = c1.x;
```

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Object creation and object identity

```
if (high > 0) {
    low1 = new C();
    low2 = new C();
} else {
    low2 = new C();
    low1 = new C();
}
```

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Object-Sensitive Non-interference



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Object creation and object identity

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if (high > 0) {
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} else {
    low2 = new C();
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```

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Joint work with

- Ralph Küsters, Trier
- Gregor Snelting, Karlsruhe

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Joint work with

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Proof Goal

The sum is the only information about the votes that is leaked.

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Joint work with

- Ralph Küsters, Trier
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Proof Goal

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Hybrid Approach

[GRSD 2013]

information-flow analysis in JOANA (w/o declassification)

- + functional verification in KeY
- = non-interference with declassification

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Hybrid Approach

[GRSD 2013]

information-flow analysis in JOANA (w/o declassification)

- + functional verification in KeY
- = non-interference with declassification

Simplified system fully verified (functional and information-flow)

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Relational Verification of Programmable Logic Controllers

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PLC Software Equivalence





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PLC Software Equivalence





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Programmable Logic Controllers (PLCs)

special-purpose programming languages (IEC 61131, ...)

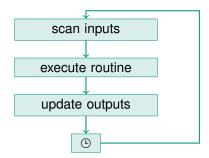
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simple structure (scan cycles)

Programmable Logic Controllers (PLCs)



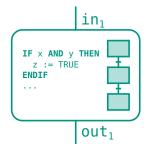
- special-purpose programming languages (IEC 61131, ...)
- simple structure (scan cycles)





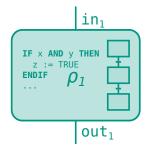


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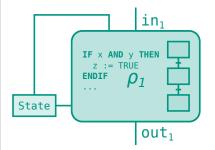
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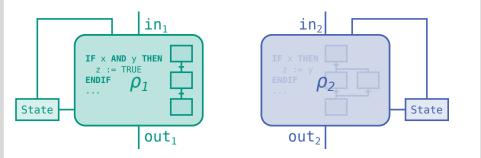
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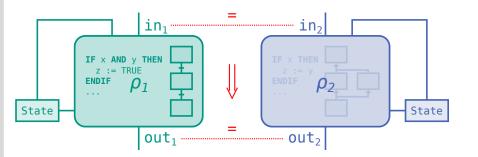
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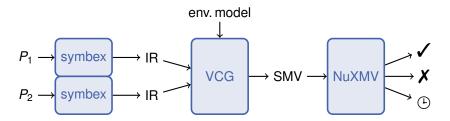


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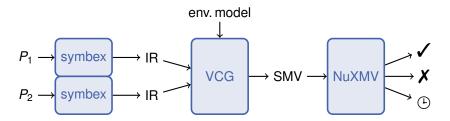
Relational Verfication Workflow for PLC:



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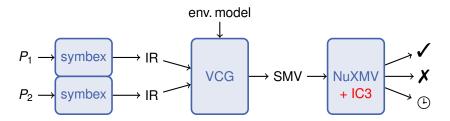
Relational Verfication Workflow for PLC:



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Relational Verfication Workflow for PLC:



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Attacker: Can change system parameters (remote maintenace)

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Attacker: Can change system parameters (remote maintenace)

Proof Goal: No interference with critical functionality (safety features)

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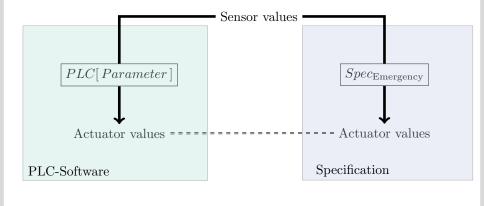
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Non-interference of Parameters with Safety Feature



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Non-interference of Parameters with Safety Feature

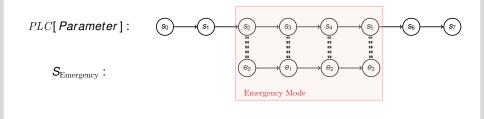


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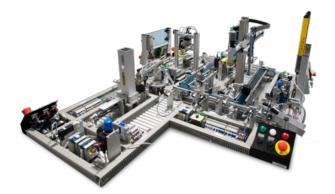
 $\forall Parameter: \mathbf{G}(Emergency \rightarrow PLC[Parameter] \approx Spec_{Emergency})$



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Case Study: Pick-and-Place Unit





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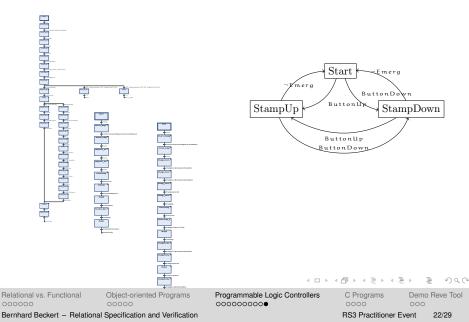
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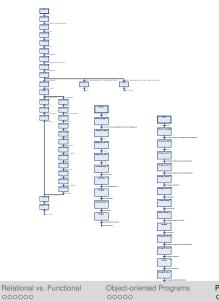
Case Study: Pick-and-Place Unit

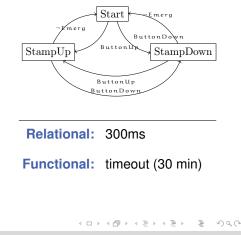




Case Study: Pick-and-Place Unit







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Relational Verification of C Programs

Relational vs. Functional

Object-oriented Programs

Programmable Logic Controllers

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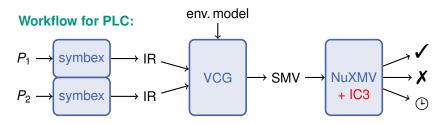
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Relational vs. Functional

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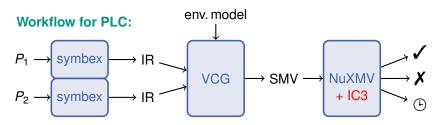
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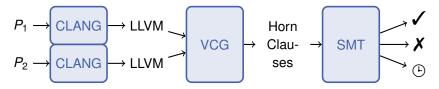
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Workflow for C Programs:



Coupling invariant inferred automatically!

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(Z3/Eldarica)

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Our approach by example



Original code

```
int f1(int n) {
    int result = 1;
    n = n/10;
    while(n > 0) {
        result ++;
        n = n/10;
    }
    return result;
}
```

What does it compute?

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Our approach by example



Original code

```
int f1(int n) {
    int result = 1;
    n = n/10;
    while(n > 0) {
        result ++;
        n = n/10;
    }
    return result;
}
```

What does it compute?

... the number of decimal digits of a non-negative number *n*.

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Behaviour preserved?



Original code

```
int f1(int n) {
    int result = 1;
    n = n/10;
    while(n > 0) {
        result ++;
        n = n/10;
    }
    return result;
}
```

Optimised version

```
int f2(int n) {
  int result = 1;
 while(true) {
    if(n<10) return result;
    if(n<100) return result+1;
    if(n<1000) return result+2;
    if(n<10000) return result+3;
   n /= 10000; result += 4;
 }
  return result;
```

Optimisation uses fewer divisions (\approx 7 times faster)

		[A. Alexandrescu. Three opti	imization tips fo	<i>ĒC++</i> , ₹012} ° ⁽
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Demo: rêve Tool

Regression verification:

formal.iti.kit.edu/improve/reve/

Non-interference:

formal.iti.kit.edu/improve/reve/noninter/

Try for yourself!

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llrêve

Automatically check two programs for equivalence

Developed and maintained as part of the IMPROVE project by Mattias Ulbrich, Vladimir Klebanov and Moritz Kiefer.

Load a predefined example:

or enter two programs:



Check equivalence Your programs are sent to the server. Please be a little patient for the answer...

- > Running llrêve
- > Running Eldarica

PROGRAMS HAVE BEEN PROVED EQUIVALENT.

sat

```
inv_main_{0}(A,B,C,D,E,F,G,H,I,J,K,L) :- (((((A = G), (B = J)), (C = H)), (D = I)), (\setminus ((E = K)); (F = L))).
```

sat means that the two programs behave equally.

unsat means that there is at least one input on which the programs behave differently. See counterexample below. If no verdict is presented, the tool may have timed out (TO set to 60s for this server)

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llrêve - non-interference -

[Usage | Disclaimer]

Automatically check non-interference for C programs

Developed and maintained as part of the IMPROVE project by Mattias Ulbrich, Vladimir Klebanov and Moritz Kiefer.

Load a predefined example:

hammer • (examples suffixed with ! contain programs that do not behave equally)

or enter a program:

Parameters which are "low":	
Program:	
<pre>int secure_if((int; high) { dot x = 0; dot x = 0; dot y < 10) { // (= 0, = 0, + 1) < (= 0, + 1)</pre>	
<pre>sum == x; if (y == 5) { x = high; y = 9; } x=+;</pre>	
y**; } return sum; // This is a secure example from a tutorial by Christian Hammer }	

Check non-interference Your program is sent to the server. Please be a little patient for the answer ...

Program proved non-interferent: No flow from high to return value.

sat

 $\begin{array}{l} \text{inv_main_1(A,B,C,D,E,F,G,H):-} (((((((B = F), (C = G)), (D = 5)), (H = 5)); (((((B = F), (C = 4)), (D = 4)), (G = 4)), (H = 4))); (((((B = F), (C = 3)), (D = 3)), (G = 3)), (H = 3))); (((((B = F), (C = 2)), (D = 2)), (G = 2)), (H = 2))); (((((B = F), (C = 1)), (O = 1)), (G = 1)), (H = 1))); (((((B = F), (C = 0)), (D = 0)), (G = 0)), (H = 0))); (((((B = F), (H = 10)), (D = 10)), (((-S - D) mod 6) = 0))). \end{array}$

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